



$$I = \oint_B \bar{F} \cdot d\bar{B} =$$

$$= \iint_M \bar{F} \cdot d\bar{M} + \iint_{A_0} \bar{F} \cdot d\bar{A}_0 +$$

$$+ \iint_{A_1} \bar{F} \cdot d\bar{A}_1$$

\bar{M}

$\bar{A}_0 \otimes \bar{A}_1$

(1) Mandel $M:$

$$M = \left\{ \bar{r}(\varphi, z) \mid \bar{r}(\varphi, z) = \begin{pmatrix} R \cos \varphi \\ R \sin \varphi \\ z \end{pmatrix}, \begin{array}{l} 0 \leq \varphi \leq 2\pi \\ a \leq z \leq b \end{array} \right.$$

Zylinderkoordinaten

$$\frac{\partial \bar{r}}{\partial \varphi} = \begin{pmatrix} -R \sin \varphi \\ R \cos \varphi \\ 0 \end{pmatrix}; \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\frac{\partial \bar{r}}{\partial z} \approx \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\bar{r}_\varphi \otimes \bar{r}_z = \begin{pmatrix} R \cos \varphi \\ R \sin \varphi \\ 0 \end{pmatrix}$$

$$\bar{F}(r, \varphi, z) = \begin{pmatrix} 0 \\ x^2 \\ -y \\ z \end{pmatrix} = \bar{F}(x, y, z)$$

$$\approx \begin{pmatrix} R^2 \cos^2 \varphi \\ -R \sin \varphi \\ z \end{pmatrix}$$

$$\vec{F}(r, \varphi, z) \cdot \vec{r}_\varphi \otimes \vec{r}_z =$$

by ¹invariance

$$\Rightarrow \begin{pmatrix} R^2 \cos^2 \varphi \\ -R \sin \varphi \\ z \end{pmatrix} \cdot \begin{pmatrix} R \cos \varphi \\ R \sin \varphi \\ 0 \end{pmatrix} =$$

$$= R^3 \cos^3 \varphi - R^2 \sin^2 \varphi;$$

$$I_M = \iint_M \bar{F}(x, y, z) d\bar{M} =$$

$$= \iint_{B'} \bar{F}(\bar{r}(\varphi, z)) \cdot (\bar{r}_\varphi \otimes \bar{r}_z) dz d\varphi$$

$$\Rightarrow \int_{\varphi=0}^{2\pi} \int_{z=0}^b (R^3 \cos^3 \varphi - R^2 \sin^2 \varphi) dz d\varphi =$$

$$= R^2 (b-a) \left[R \int_0^{2\pi} \cos^3 \varphi d\varphi - \int_0^{2\pi} \sin^2 \varphi d\varphi \right]$$
$$= R^2 (b-a) \left[R \cdot 0 - \frac{\pi}{2} \right] = \underline{\underline{-\frac{\pi}{2} (b-a) R^2}}$$

$$\int \sin^2(ax) dx = \frac{x}{2} - \frac{1}{4a} \sin(2ax) + C$$

(2) Bode

 A_{ω}

$$A_{\omega} = \left\{ \bar{r}(r, \varphi) = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \\ r \end{pmatrix} \right.$$

$$0 \leq r \leq R$$

$$0 \leq \varphi \leq 2\pi$$

$$\frac{\partial \bar{r}}{\partial \varphi} = \begin{pmatrix} -r \sin \varphi \\ r \cos \varphi \\ 0 \end{pmatrix}; \quad \frac{\partial \bar{r}}{\partial r} = \begin{pmatrix} \cos \varphi \\ \sin \varphi \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \frac{\partial \bar{r}}{\partial \varphi} \\ \frac{\partial \bar{r}}{\partial r} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{F} = \begin{pmatrix} x^2 \\ y \\ z \end{pmatrix} = \begin{pmatrix} r^2 \cos^2 \varphi \\ -r \sin \varphi \\ a \end{pmatrix}$$

$$\vec{F} \cdot \vec{N}_b = -r \cdot a$$

$$I_{A_9} = \iint_{A_9} \vec{F} \cdot d\vec{A}_9 = \int_{\varphi=0}^{2\pi} \int_{r=0}^R (-ra) d\varphi dr =$$

$$= -2\pi a \int_0^R r dr = \cancel{4\pi R^2} - R^2 a;$$

Definiere A_b :

$$A_b = \left\{ \vec{r}(r, \varphi) = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \\ 0 \end{pmatrix}, \begin{matrix} 0 \leq r \leq R \\ 0 \leq \varphi \leq 2\pi \end{matrix} \right\}$$

$$\frac{\partial \vec{r}}{\partial \varphi} = \begin{pmatrix} -r \sin \varphi \\ r \cos \varphi \\ 0 \end{pmatrix}$$

Oder $\vec{N}_b = -\vec{N}_q$

in dieser fol

$$\vec{T} = \begin{pmatrix} r^2 \cos^2 \varphi \\ -r \sin \varphi \\ 0 \end{pmatrix}$$

$$\vec{F} \cdot \vec{n}_0 = \begin{pmatrix} r^2 \cos^2 \varphi \\ -r \sin \varphi \\ b \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ r \end{pmatrix} =$$

$$= br;$$

$$I_{A_0} = \iint_{A_0} \vec{F} \cdot \vec{n}_0 =$$

$$= \int_{r=0}^R \int_{\varphi=0}^{2\pi} br \, d\varphi \, dr =$$

$$= \pi b R^2.$$

$$J = J_{A_1} + J_{A_0} + J_n =$$

$$= -qTR^2 + bTR^2 -$$

$$- (b-q)R^2 \frac{1}{T} =$$

$$= TR^2 (b-q) - (b-q)R^2 \frac{1}{T} =$$

$$= 0$$